

## DEFINITION:

Let  $V$  be a vector space and  $B$  be a basis of  $V$ . The dimension of  $V$  is a number of vectors in  $B$ .

## EXAMPLE:

Since

$$\bar{e}_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad \bar{e}_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \quad \bar{e}_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

is the basis for  $\mathbb{R}^n$ , we get  $\dim \mathbb{R}^n = n$ .

**EXAMPLE:**

Find the dimension of the subspace

$$H = \left\{ \begin{bmatrix} a - 4b + c \\ 2a - c + 3d \\ 2b - c + d \\ b + 3d \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}$$

## SOLUTION:

We have

$$\begin{bmatrix} a - 4b + c \\ 2a - c + 3d \\ 2b - c + 2d \\ b + 3d \end{bmatrix}$$

$$= a \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} -4 \\ 0 \\ 2 \\ 1 \end{bmatrix} + c \begin{bmatrix} 1 \\ -1 \\ -1 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 3 \\ 2 \\ 3 \end{bmatrix}$$

Using elementary row operations, we get

$$\begin{bmatrix} 1 & -4 & 1 & 0 \\ 2 & 0 & -1 & 3 \\ 0 & 2 & -1 & 2 \\ 0 & 1 & 0 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & -4 & 1 & 0 \\ 0 & 8 & -3 & 3 \\ 0 & 0 & 1 & -5 \\ 0 & 0 & 0 & 1 \end{bmatrix},$$

therefore  $\dim H = 4$ .

## EXAMPLE:

Subspaces of  $R^3$  can be classified by dimension:

0-dimensional subspaces: Only the zero subspace.

1-dimensional subspaces: Any subspace spanned by a single nonzero vector. Such subspaces are lines through the origin.

2-dimensional subspaces: Any subspace spanned by 2 linearly independent vectors (= not parallel). Such subspaces are planes through the origin.

3-dimensional subspaces: Only  $R^3$  itself. Any 3 linearly independent vectors in  $R^3$  (= not in the same plane) span all of  $R^3$ .

## THEOREM:

Let  $V$  be a  $p$ -dimensional vector space,  $p \geq 1$ . Then

(a) Any linearly independent set of exactly  $p$  elements in  $V$  is automatically a basis for  $V$ .

(b) Any set of exactly  $p$  elements that spans  $V$  is automatically a basis for  $V$ .

**THEOREM:**

(a) The dimension of  $\text{Nul } A$  is the number of free variables in the equation  $A\bar{x} = \bar{0}$ .

(b) The dimension of  $\text{Col } A$  is the number of pivot columns in  $A$ .

**EXAMPLE:**

Find the dimensions of the null space and the column space of

$$A = \begin{bmatrix} 1 & 2 & 0 & -1 \\ 2 & 0 & 1 & -2 \\ 4 & 4 & -1 & -4 \\ 7 & 6 & 2 & -7 \end{bmatrix}$$

## SOLUTION:

Using elementary row operations, we get

$$\begin{bmatrix} 1 & 2 & 0 & -1 \\ 2 & 0 & 1 & -2 \\ 4 & 4 & -1 & -4 \\ 7 & 6 & 2 & -7 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 & -1 \\ 0 & 4 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

There is one free variable  $x_4$ . Hence  $\dim \text{Nul } A = 1$ . Also,  $\dim \text{Col } A = 3$  because  $A$  has 3 pivots.



## DEFINITION:

Let  $A$  be an  $m \times n$  matrix. The row space is the set of all linear combinations of the row vectors of  $A$ .

## EXAMPLE:

Let

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

The row space of  $A$  is the subspace of  $\mathcal{R}^4$  spanned by

$$\bar{v}_1 = (1, 2, 3, 4)$$

$$\bar{v}_2 = (5, 6, 7, 8)$$

$$\bar{v}_3 = (0, 0, 1, 2)$$

## THEOREM:

If two matrices  $A$  and  $B$  are row equivalent, then their row spaces are the same. If  $B$  is in echelon form, the nonzero rows of  $B$  form a basis for the row space of  $A$  as well as for that of  $B$ .

## EXAMPLE:

Find bases for the row space, the column space, and the null space of the matrix

$$A = \begin{bmatrix} -1 & 4 & -2 & 0 & -3 \\ 2 & 1 & 1 & -1 & 0 \\ 0 & 9 & -3 & -1 & -6 \end{bmatrix}$$

## SOLUTION:

Using elementary row operations, we get

$$\begin{bmatrix} -1 & 4 & -2 & 0 & -3 \\ 2 & 1 & 1 & -1 & 0 \\ 0 & 9 & -3 & -1 & -6 \end{bmatrix} \sim \begin{bmatrix} 1 & -4 & 2 & 0 & 3 \\ 0 & 9 & -3 & -1 & -6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(a) By the Theorem above, the first two rows of the second matrix form a basis for the row space of  $A$ .

(b) Since pivots are in columns 1 and 2, the first two columns of  $A$  form a basis for  $\text{Col } A$ .

(c) Finally, for  $\text{Nul } A$  we need the reduced echelon form. We have:

$$\begin{bmatrix} -1 & 4 & -2 & 0 & -3 \\ 2 & 1 & 1 & -1 & 0 \\ 0 & 9 & -3 & -1 & -6 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & \frac{2}{3} & -\frac{4}{9} & \frac{1}{3} \\ 0 & 1 & -\frac{1}{3} & -\frac{1}{9} & -\frac{2}{3} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

therefore the corresponding system is

$$\begin{cases} x_1 + \frac{2}{3}x_3 - \frac{4}{9}x_4 + \frac{1}{3}x_5 = 0 \\ x_2 - \frac{1}{3}x_3 - \frac{1}{9}x_4 - \frac{2}{3}x_5 = 0 \end{cases}$$

Write the general solution in the parametric form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -\frac{2}{3}x_3 + \frac{4}{9}x_4 - \frac{1}{3}x_5 \\ \frac{1}{3}x_3 + \frac{1}{9}x_4 + \frac{2}{3}x_5 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} \\
 = x_3 \underbrace{\begin{bmatrix} -\frac{2}{3} \\ \frac{1}{3} \\ 1 \\ 0 \\ 0 \end{bmatrix}}_{\bar{v}_1} + x_4 \underbrace{\begin{bmatrix} \frac{4}{9} \\ \frac{1}{9} \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\bar{v}_2} + x_5 \underbrace{\begin{bmatrix} -\frac{1}{3} \\ \frac{2}{3} \\ 0 \\ 0 \\ 1 \end{bmatrix}}_{\bar{v}_3}$$

so  $\{\bar{v}_1, \bar{v}_2, \bar{v}_3\}$  is the basis for  $\text{Nul } A$ .