

**DEFINITION:**

A set of vectors  $\{\bar{u}_1, \dots, \bar{u}_p\}$  in  $R^n$  is said to be an orthogonal set if each pair of distinct vectors from the set is orthogonal, that is

$$\bar{u}_i \cdot \bar{u}_j = 0$$

for any  $i \neq j$ .

**EXAMPLE:**

Let

$$\bar{u}_1 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}, \bar{u}_2 = \begin{bmatrix} 0 \\ 8 \\ 0 \end{bmatrix}, \bar{u}_3 = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}.$$

Then  $\{\bar{u}_1, \bar{u}_2, \bar{u}_3\}$  is an orthogonal set.

**PROBLEM:**

Let

$$\bar{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \bar{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \bar{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}.$$

Show that  $\{\bar{u}_1, \bar{u}_2, \bar{u}_3\}$  is an orthogonal set.

**SOLUTION:**

We have

$$\bar{u}_1 \cdot \bar{u}_2 = 3(-1) + 1 \cdot 2 + 1 \cdot 1 = 0$$

$$\bar{u}_1 \cdot \bar{u}_3 = 3 \left(-\frac{1}{2}\right) + 1(-2) + 1 \left(\frac{7}{2}\right) = 0$$

$$\bar{u}_2 \cdot \bar{u}_3 = -1 \left(-\frac{1}{2}\right) + 2(-2) + 1 \left(\frac{7}{2}\right) = 0$$

**THEOREM:**

If  $\mathcal{S} = \{\bar{u}_1, \dots, \bar{u}_p\}$  is an orthogonal set of nonzero vectors in  $R^n$ , then  $\mathcal{S}$  is linearly independent and hence is a basis (so-called, an orthogonal basis) for the subspace spanned by  $\mathcal{S}$ . Of course, if  $p = n$ , then  $\mathcal{S}$  is a basis for  $R^n$ .

**EXAMPLE:**

Let  $\mathcal{S} = \{\bar{u}_1, \bar{u}_2, \bar{u}_3\}$ , where

$$\bar{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \bar{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \bar{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}.$$

Then  $\mathcal{S}$  is an orthogonal basis for  $R^3$ .

**PROBLEM:**

Let  $\mathcal{S} = \{\bar{u}_1, \bar{u}_2, \bar{u}_3\}$ , where

$$\bar{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \bar{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \bar{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}.$$

Find coordinates of  $\bar{y} = (6, 1, -8)$  in  $\mathcal{S}$ .

**SOLUTION:**

We have:

$$\begin{aligned} & \begin{bmatrix} 3 & -1 & -1/2 & 6 \\ 1 & 2 & -2 & 1 \\ 1 & 1 & 7/2 & -8 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & -2 & 1 \\ 3 & -1 & -1/2 & 6 \\ 1 & 1 & 7/2 & -8 \end{bmatrix} \\ & \sim \begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & -7 & 5.5 & 3 \\ 0 & -1 & 5.5 & -9 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & -1 & 5.5 & -9 \\ 0 & -7 & 5.5 & 3 \end{bmatrix} \\ & \sim \begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & -1 & 5.5 & -9 \\ 0 & 0 & -33 & 66 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & 1 & -5.5 & 9 \\ 0 & 0 & 1 & -2 \end{bmatrix} \\ & \sim \begin{bmatrix} 1 & 2 & 0 & -3 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & -2 \end{bmatrix} \end{aligned}$$

**THEOREM:**

Let  $\mathcal{S} = \{\bar{u}_1, \dots, \bar{u}_p\}$  be an orthogonal basis for a subspace  $W$  of  $R^n$ . For each  $\bar{y}$  in  $W$  the weights in the linear combination

$$\bar{y} = c_1\bar{u}_1 + \dots + c_p\bar{u}_p$$

are given by

$$c_j = \frac{\bar{y} \cdot \bar{u}_j}{\bar{u}_j \cdot \bar{u}_j} \quad (j = 1, \dots, p).$$

**PROOF:**

Let  $c_1, \dots, c_p$  be such numbers that

$$\bar{y} = c_1\bar{u}_1 + c_2\bar{u}_2 + \dots + c_p\bar{u}_p. \quad (*)$$

If we multiply both sides of (\*) by  $\bar{u}_1$ , we get

$$\begin{aligned} & \bar{y} \cdot \bar{u}_1 \\ &= c_1\bar{u}_1 \cdot \bar{u}_1 + c_2\bar{u}_2 \cdot \bar{u}_1 + \dots + c_p\bar{u}_p \cdot \bar{u}_1 \\ &= c_1\bar{u}_1 \cdot \bar{u}_1 + 0 + \dots + 0 \\ &= c_1\bar{u}_1 \cdot \bar{u}_1 \end{aligned}$$

because of orthogonality of  $\bar{u}_1, \dots, \bar{u}_p$ . So,  $\bar{y} \cdot \bar{u}_1 = c_1\bar{u}_1 \cdot \bar{u}_1$ , therefore

$$c_1 = \frac{\bar{y} \cdot \bar{u}_1}{\bar{u}_1 \cdot \bar{u}_1}.$$

Similarly, if we multiply both sides of (\*) by  $\bar{u}_j$ , we deduce

$$c_j = \frac{\bar{y} \cdot \bar{u}_j}{\bar{u}_j \cdot \bar{u}_j} \quad (j = 1, \dots, p).$$

**PROBLEM:**

Let  $\mathcal{S} = \{\bar{u}_1, \bar{u}_2, \bar{u}_3\}$ , where

$$\bar{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \bar{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \bar{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}.$$

Find coordinates of  $\bar{y} = (6, 1, -8)$  in  $\mathcal{S}$ .

**SOLUTION:**

We have:

$$\bar{y} \cdot \bar{u}_1 = 11, \bar{y} \cdot \bar{u}_2 = -12, \bar{y} \cdot \bar{u}_3 = -33$$

and

$$\bar{u}_1 \cdot \bar{u}_1 = 11, \bar{u}_2 \cdot \bar{u}_2 = 6, \bar{u}_3 \cdot \bar{u}_3 = 33/2,$$

so

$$c_1 = \frac{\bar{y} \cdot \bar{u}_1}{\bar{u}_1 \cdot \bar{u}_1} = \frac{11}{11} = 1$$

$$c_2 = \frac{\bar{y} \cdot \bar{u}_2}{\bar{u}_2 \cdot \bar{u}_2} = \frac{-12}{6} = -2$$

$$c_3 = \frac{\bar{y} \cdot \bar{u}_3}{\bar{u}_3 \cdot \bar{u}_3} = \frac{-33}{33/2} = -2$$

therefore

$$[\bar{x}]_{\mathcal{S}} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ -2 \end{bmatrix}.$$

**AN ORTHOGONAL PROJECTION**

**PROBLEM:**

Let  $\bar{u}$  and  $\bar{y}$  be nonzero vectors in  $R^n$ .

Find vectors  $\hat{y}$  and  $\bar{z}$  such that

$$\bar{y} = \hat{y} + \bar{z},$$

where  $\hat{y}$  is a multiple of  $\bar{u}$  and  $\bar{z}$  is orthogonal to  $\bar{u}$ .

**SOLUTION:**

Rewrite  $\bar{y} = \hat{y} + \bar{z}$  as  $\bar{z} = \bar{y} - \hat{y}$  and multiply both sides by  $\bar{u}$ :

$$\bar{z} \cdot \bar{u} = (\bar{y} - \hat{y}) \cdot \bar{u}$$

But  $\bar{z}$  is orthogonal to  $\bar{u}$ , therefore

$$0 = (\bar{y} - \hat{y}) \cdot \bar{u}. \quad (*)$$

Since  $\hat{y}$  is a multiple of  $\bar{u}$ , we have

$$\hat{y} = \alpha \bar{u}, \text{ where } \alpha \text{ is a scalar.}$$

Substituting this into (\*), we get

$$0 = (\bar{y} - \alpha \bar{u}) \cdot \bar{u} = \bar{y} \cdot \bar{u} - \alpha \bar{u} \cdot \bar{u},$$

hence

$$\alpha = \frac{\bar{y} \cdot \bar{u}}{\bar{u} \cdot \bar{u}} \quad \text{and} \quad \hat{y} = \frac{\bar{y} \cdot \bar{u}}{\bar{u} \cdot \bar{u}} \bar{u}.$$

**DEFINITION:**

The vector  $\hat{y}$  is called the orthogonal projection of  $\bar{y}$  onto  $\bar{u}$  and denoted by

$$\text{proj}_{\bar{u}} \bar{y}.$$

The vector  $\bar{z}$  is called the component of  $\bar{y}$  orthogonal to  $\bar{u}$ .

**EXAMPLE:**

Let  $\bar{y} = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$  and  $\bar{u} = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$ . Find the orthogonal projection of  $\bar{y}$  onto  $\bar{u}$ . Write  $\bar{y}$  as a sum of two orthogonal vectors, one in  $\text{Span} \{\bar{u}\}$  and one orthogonal to  $\bar{u}$ .

**SOLUTION:**

We first find the orthogonal projection of  $\bar{y}$  onto  $\bar{u}$ . We have

$$\hat{y} = \frac{\bar{y} \cdot \bar{u}}{\bar{u} \cdot \bar{u}} \bar{u} = \frac{7 \cdot 4 + 6 \cdot 2}{4 \cdot 4 + 2 \cdot 2} \bar{u} = 2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix}.$$

We now find the component  $\bar{z}$ . We have

$$\bar{z} = \bar{y} - \hat{y} = \begin{bmatrix} 7 \\ 6 \end{bmatrix} - \begin{bmatrix} 8 \\ 4 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}.$$

Finally, we write  $\bar{y}$  as a sum of two orthogonal vectors, one in  $\text{Span}\{\bar{u}\}$  and one orthogonal to  $\bar{u}$ :

$$\begin{bmatrix} 7 \\ 6 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix} + \begin{bmatrix} -1 \\ 2 \end{bmatrix}.$$

**REMARK:**

Note that the orthogonal projection of  $\bar{y}$  onto  $\bar{u}$  is exactly the same as the orthogonal projection of  $\bar{y}$  onto  $c\bar{u}$ , where  $c$  is any nonzero scalar. Hence this projection is determined by the subspace  $L$  spanned by  $\bar{u}$ . Therefore sometimes we denote  $\hat{y}$  by

$$\text{proj}_L \bar{y}.$$

So,

$$\hat{y} = \text{proj}_{\bar{u}} \bar{y} = \text{proj}_L \bar{y} = \frac{\bar{y} \cdot \bar{u}}{\bar{u} \cdot \bar{u}} \bar{u}.$$

**DEFINITION:**

A set of vectors  $\{\bar{u}_1, \dots, \bar{u}_p\}$  in  $R^n$  is said to be an orthonormal set if it is an orthogonal set of unit vectors.

A set of vectors  $\{\bar{u}_1, \dots, \bar{u}_p\}$  in  $R^n$  is said to be an orthonormal basis if it is an orthogonal basis of unit vectors.

**EXAMPLE:**

Let

$$\bar{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \bar{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \bar{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

Then  $\{\bar{e}_1, \bar{e}_2, \bar{e}_3\}$  is the orthonormal basis for  $R^3$ .

**EXAMPLE:**

We know that

$$\bar{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \bar{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \bar{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}.$$

is the orthogonal basis for  $R^3$ . Then

$$\bar{w}_1 = \frac{\bar{u}_1}{\|\bar{u}_1\|} = \frac{1}{\sqrt{11}} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}$$

$$\bar{w}_2 = \frac{\bar{u}_2}{\|\bar{u}_2\|} = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

$$\bar{w}_3 = \frac{\bar{u}_3}{\|\bar{u}_3\|} = \frac{1}{\sqrt{33}} \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix} = \frac{1}{\sqrt{66}} \begin{bmatrix} -1 \\ -4 \\ 7 \end{bmatrix}$$

is the orthonormal basis for  $R^3$ .