

## THE INNER PRODUCT

### DEFINITION:

If  $\bar{u}$  and  $\bar{v}$  are vectors in  $R^n$ , then  $\bar{u}^T \bar{v}$  is called the inner product (or dot product) of  $\bar{u}$  and  $\bar{v}$  and written as

$$\bar{u} \cdot \bar{v}$$

### REMARK:

In other words, if

$$\bar{u} = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} \quad \text{and} \quad \bar{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix},$$

then

$$\begin{aligned} \bar{u} \cdot \bar{v} &= \bar{u}^T \bar{v} = [u_1 \ \dots \ u_n] \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \\ &= u_1 v_1 + \dots + u_n v_n. \end{aligned}$$

### EXAMPLE:

Let

$$\bar{u} = \begin{bmatrix} 2 \\ -5 \\ -1 \end{bmatrix} \quad \text{and} \quad \bar{v} = \begin{bmatrix} 3 \\ 2 \\ -3 \end{bmatrix}.$$

Find  $\bar{u} \cdot \bar{v}$ .

### SOLUTION:

We have

$$\bar{u} \cdot \bar{v} = 2 \cdot 3 + (-5) \cdot 2 + (-1)(-3) = -1.$$

### THEOREM:

Let  $\bar{u}$ ,  $\bar{v}$ , and  $\bar{w}$  be vectors in  $R^n$ , and let  $c$  be a scalar. Then

- (a)  $\bar{u} \cdot \bar{v} = \bar{v} \cdot \bar{u}$
- (b)  $(\bar{u} + \bar{v}) \cdot \bar{w} = \bar{u} \cdot \bar{w} + \bar{v} \cdot \bar{w}$
- (c)  $(c\bar{u}) \cdot \bar{v} = c(\bar{u} \cdot \bar{v}) = \bar{u} \cdot (c\bar{v})$
- (d)  $\bar{u} \cdot \bar{u} \geq 0$
- (d')  $\bar{u} \cdot \bar{u} = 0$  if and only if  $\bar{u} = 0$

## THE LENGTH OF A VECTOR

### DEFINITION:

Let  $\bar{v} = (v_1, \dots, v_n)$  be a vector from  $R^n$ . Then the length (or norm) of  $\bar{v}$  is the nonnegative scalar  $\|\bar{v}\|$  defined by

$$\|\bar{v}\| = \sqrt{\bar{v} \cdot \bar{v}} = \sqrt{v_1^2 + \dots + v_n^2}.$$

### EXAMPLE:

The length of the vector

$$\bar{u} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

is

$$\|\bar{u}\| = \sqrt{3^2 + 4^2} = \sqrt{25} = 5.$$

**PROPERTY:**

Let  $c$  be a scalar. Then

$$\|c\bar{v}\| = |c|\|\bar{v}\|.$$

**PROOF 1:**

We have

$$\begin{aligned}\|c\bar{v}\| &= \sqrt{(cv_1)^2 + \dots + (cv_n)^2} \\ &= \sqrt{c^2(v_1^2 + \dots + v_n^2)} \\ &= |c|\sqrt{v_1^2 + \dots + v_n^2} \\ &= |c|\|\bar{v}\|.\end{aligned}$$

**PROOF 2:**

We have

$$\|c\bar{v}\|^2 = (c\bar{v}) \cdot (c\bar{v}) = c^2\bar{v} \cdot \bar{v} = c^2\|\bar{v}\|^2.$$

**DEFINITION:**

A vector whose length is 1 is called a unit vector.

**PROBLEM:**

Let  $\bar{v} = (1, -2, 2, 0)$ . Find:

- (a) The length of  $\bar{v}$ ;
- (b) The unit vector in the same direction as  $\bar{v}$ .

**SOLUTION:**

(a) We have

$$\|\bar{v}\| = \sqrt{1^2 + (-2)^2 + 2^2 + 0^2} = \sqrt{9} = 3.$$

(b) Put

$$\bar{u} = \frac{1}{\|\bar{v}\|}\bar{v}.$$

Note that vectors  $\bar{v}$  and  $\bar{u}$  have the same direction. Moreover, since

$$\|\bar{u}\| = \left\| \frac{1}{\|\bar{v}\|}\bar{v} \right\| = \frac{1}{\|\bar{v}\|}\|\bar{v}\| = 1,$$

it follows that  $\bar{u}$  is the unit vector. Finally, we have

$$\|\bar{u}\| = \frac{1}{\|\bar{v}\|}\bar{v} = \frac{1}{3} \begin{bmatrix} 1 \\ -2 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/3 \\ -2/3 \\ 2/3 \\ 0 \end{bmatrix}.$$

**DISTANCE IN  $R^n$**

**DEFINITION:**

Let  $\bar{u}$  and  $\bar{v}$  be from  $R^n$ . Then the distance between  $\bar{u}$  and  $\bar{v}$ , written as

$$\text{dist}(\bar{u}, \bar{v}),$$

is the length of the vector  $\bar{u} - \bar{v}$ . That is,

$$\text{dist}(\bar{u}, \bar{v}) = \|\bar{u} - \bar{v}\|.$$

**EXAMPLE:**

Let

$$\bar{u} = (1, 2, 3) \quad \text{and} \quad \bar{v} = (-1, 5, -4).$$

Find the distance between  $\bar{u}$  and  $\bar{v}$ .

**SOLUTION:**

Step 1: We have

$$\bar{u} - \bar{v} = (1, 2, 3) - (-1, 5, -4) = (2, -3, 7).$$

Step 2: By the Definition above, we get

$$\text{dist}(\bar{u}, \bar{v}) = \sqrt{2^2 + (-3)^2 + 7^2} = \sqrt{62}.$$

**ORTHOGONAL VECTORS**

**DEFINITION:**

Two vectors  $\bar{u}$  and  $\bar{v}$  in  $R^n$  are orthogonal (perpendicular) if

$$\bar{u} \cdot \bar{v} = 0.$$

**EXAMPLE:**

Vectors  $\bar{u} = (4, 12)$  and  $\bar{v} = (9, -3)$  are orthogonal, since

$$\bar{u} \cdot \bar{v} = 4 \cdot 9 + 12 \cdot (-3) = 0.$$

**THEOREM (The Pythagorean Theorem):**

Two vectors  $\bar{u}$  and  $\bar{v}$  in  $R^n$  are orthogonal if and only if

$$\|\bar{u} + \bar{v}\|^2 = \|\bar{u}\|^2 + \|\bar{v}\|^2.$$

**ANGLES IN  $R^2$  AND  $R^3$**

**THEOREM:**

Let  $\bar{u}$  and  $\bar{v}$  be from  $R^2$  or  $R^3$  and let  $\theta$  be the angle between them. Then

$$\cos \theta = \frac{\bar{u} \cdot \bar{v}}{\|\bar{u}\| \|\bar{v}\|}$$

**EXAMPLE:**

Find the angle between vectors

$$\bar{u} = \begin{bmatrix} 5 \\ -3 \\ 1 \end{bmatrix} \quad \text{and} \quad \bar{v} = \begin{bmatrix} 6 \\ 9 \\ -3 \end{bmatrix}.$$

**SOLUTION:**

We have  $\cos \theta = \frac{\bar{u} \cdot \bar{v}}{\|\bar{u}\| \|\bar{v}\|} =$

$$\frac{5 \cdot 6 + (-3) \cdot 9 + 1 \cdot (-3)}{\sqrt{5^2 + (-3)^2 + 1^2} \sqrt{6^2 + 9^2 + (-3)^2}} = 0,$$

therefore

$$\theta = \frac{\pi}{2} = 90^\circ.$$

## ORTHOGONAL COMPLEMENTS

### DEFINITION:

If a vector  $\bar{z}$  is orthogonal to every vector in a subspace  $W$  of  $R^n$ , then  $\bar{z}$  is said to be orthogonal to  $W$ .

### EXAMPLE:

Let  $\bar{z} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$  and

$$W = \left\{ \begin{bmatrix} 6 \\ -4 \end{bmatrix} t : t \in R \right\}$$

be a subspace of  $R^2$ . Then  $\bar{z}$  is orthogonal to every vector in  $W$ , since

$$\bar{z} \cdot \left( \begin{bmatrix} 6 \\ -4 \end{bmatrix} t \right) = \left( \begin{bmatrix} 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 6 \\ -4 \end{bmatrix} \right) t = 0 t = 0.$$

### DEFINITION:

The set of all vectors  $\bar{z}$  that are orthogonal to  $W$  is called the orthogonal complement of  $W$  and is denoted by  $W^\perp$ .

### EXAMPLE:

Let

$$H = \left\{ \begin{bmatrix} 2 \\ 3 \end{bmatrix} s : s \in R \right\}$$

and

$$W = \left\{ \begin{bmatrix} 6 \\ -4 \end{bmatrix} t : t \in R \right\}$$

be subspaces of  $R^2$ . Then every vector in  $H$  is orthogonal to every vector in  $W$ , since

$$\left( \begin{bmatrix} 2 \\ 3 \end{bmatrix} s \right) \cdot \left( \begin{bmatrix} 6 \\ -4 \end{bmatrix} t \right) = \left( \begin{bmatrix} 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 6 \\ -4 \end{bmatrix} \right) st = 0.$$

Moreover, one can show that there are no other vectors in  $R^2$  which are orthogonal to every vector in  $W$ . Therefore  $H = W^\perp$ .

### EXAMPLE:

Let  $\bar{z} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  and

$$W = \left\{ \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} t_1 + \begin{bmatrix} 7 \\ 4 \\ -5 \end{bmatrix} t_2 : t_1, t_2 \in R \right\}$$

be a subspace of  $R^3$ . Then  $\bar{z}$  is orthogonal to every vector in  $W$ , since

$$\begin{aligned} \bar{z} \cdot \left( \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} t_1 + \begin{bmatrix} 7 \\ 4 \\ -5 \end{bmatrix} t_2 \right) \\ = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} t_1 + \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 7 \\ 4 \\ -5 \end{bmatrix} t_2 \\ = 0 t_1 + 0 t_2 = 0. \end{aligned}$$

### EXAMPLE:

Let  $L_1$  be a line through the origin in  $R^2$ , and let  $L_2$  be the line through the origin and perpendicular to  $L_1$ . Then each vector on  $L_1$  is orthogonal to every vector in  $L_2$ . Moreover, one can show that there are no other vectors in  $R^2$  which are orthogonal to every vector in  $L_1$ . Therefore

$$L_1 = L_2^\perp.$$

Also, for the same reason we have

$$L_2 = L_1^\perp.$$

**EXAMPLE:**

$$\text{Let } H = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} s : s \in \mathbb{R} \right\} \text{ and}$$

$$W = \left\{ \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} t_1 + \begin{bmatrix} 7 \\ 4 \\ -5 \end{bmatrix} t_2 : t_1, t_2 \in \mathbb{R} \right\}$$

be subspaces of  $\mathbb{R}^3$ . Then every vector in  $H$  is orthogonal to every vector in  $W$ , since

$$\begin{aligned} & \left( \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} s \right) \cdot \left( \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} t_1 + \begin{bmatrix} 7 \\ 4 \\ -5 \end{bmatrix} t_2 \right) \\ &= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} s t_1 + \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 7 \\ 4 \\ -5 \end{bmatrix} s t_2 \\ &= 0 s t_1 + 0 s t_2 = 0. \end{aligned}$$

Moreover, one can show that there are no other vectors in  $\mathbb{R}^3$  which are orthogonal to every vector in  $W$ . Therefore  $H = W^\perp$ .

**THEOREM:**

(a) A vector  $\bar{x}$  is in  $W^\perp$  if and only if  $\bar{x}$  is orthogonal to every vector in a set that spans  $W$ .

(b)  $W^\perp$  is a subspace of  $\mathbb{R}^n$ .

**EXAMPLE:**

Let  $W$  be a plane through the origin in  $\mathbb{R}^3$ , and let  $L$  be the line through the origin and perpendicular to  $W$ . Then each vector on  $L$  is orthogonal to every vector  $\bar{z}$  in  $W$ . Moreover, one can show that there are no other vectors in  $\mathbb{R}^3$  which are orthogonal to every vector in  $W$ . Therefore

$$L = W^\perp.$$

Also, for the same reason we have

$$W = L^\perp.$$

**THEOREM:**

Let  $A$  be an  $m \times n$  matrix. Then

$$(\text{Row } A)^\perp = \text{Nul } A$$

and

$$(\text{Col } A)^\perp = \text{Nul } A^T.$$

**PROOF:**

The row-column rule for computing  $A\bar{x}$  shows that if  $\bar{x}$  is in  $\text{Nul } A$ , then  $\bar{x}$  is orthogonal to each row of  $A$ . Since the rows of  $A$  span the row space,  $\bar{x}$  is orthogonal to  $\text{Row } A$ .

Conversely, if  $\bar{x}$  is orthogonal to  $\text{Row } A$ , then  $\bar{x}$  is certainly orthogonal to each row of  $A$ , and therefore we have  $A\bar{x} = \bar{0}$ .

To prove the second part of the theorem, we note that

$$(\text{Row } A^T)^\perp = \text{Nul } A^T \quad (*)$$

by the first part of this theorem. On the other hand, it is easy to see that

$$\text{Row } A^T = \text{Col } A,$$

therefore

$$(\text{Row } A^T)^\perp = (\text{Col } A)^\perp. \quad (**)$$

Combination of (\*) and (\*\*) gives the desired result. ■