

DEFINITION:

A vector space is a nonempty set V of objects, called vectors, on which are defined two operations, called addition and multiplication by scalars (real numbers), subject to the following 10 axioms (or rules):

1. The sum of \bar{u} and \bar{v} , denoted by $\bar{u} + \bar{v}$, is in V .
2. $\bar{u} + \bar{v} = \bar{v} + \bar{u}$.
3. $(\bar{u} + \bar{v}) + \bar{w} = \bar{u} + (\bar{v} + \bar{w})$.
4. There is a zero vector $\bar{0}$ in V such that $\bar{u} + \bar{0} = \bar{u}$.
5. For each \bar{u} in V , there is a vector $-\bar{u}$ in V such that $\bar{u} + (-\bar{u}) = \bar{0}$.
6. The scalar multiple of \bar{u} by c , denoted by $c\bar{u}$, is in V .
7. $c(\bar{u} + \bar{v}) = c\bar{u} + c\bar{v}$.
8. $(c + d)\bar{u} = c\bar{u} + d\bar{u}$.
9. $c(d\bar{u}) = (cd)\bar{u}$.
10. $1 \cdot \bar{u} = \bar{u}$.

These axioms must hold for all vectors \bar{u} , \bar{v} , and \bar{w} in V and all scalars c and d .

EXAMPLE:

R^n is a vector space. In fact, let

$$\bar{u} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \bar{v} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \quad \bar{w} = \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix}$$

Then

1. $\bar{u} + \bar{v}$ is in V .
2. $\bar{u} + \bar{v} = \bar{v} + \bar{u}$.
3. $(\bar{u} + \bar{v}) + \bar{w} = \bar{u} + (\bar{v} + \bar{w})$.

4. There is the zero vector $\bar{0} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$

in V such that $\bar{u} + \bar{0} = \bar{u}$, since

$$\bar{u} + \bar{0} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \bar{u}.$$

5. For each $\bar{u} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$ in V , there is the vector $-\bar{u} = \begin{bmatrix} -x_1 \\ -x_2 \\ \vdots \\ -x_n \end{bmatrix}$ in V such that $\bar{u} + (-\bar{u}) = \bar{0}$, since

$$\bar{u} + (-\bar{u}) = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} -x_1 \\ -x_2 \\ \vdots \\ -x_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \bar{0}.$$

6. The scalar multiple of \bar{u} by c , denoted by $c\bar{u}$, is in V .

7. $c(\bar{u} + \bar{v}) = c\bar{u} + c\bar{v}$.
8. $(c + d)\bar{u} = c\bar{u} + d\bar{u}$.
9. $c(d\bar{u}) = (cd)\bar{u}$.
10. $1 \cdot \bar{u} = \bar{u}$.

EXAMPLE:

The set of all $n \times m$ matrices, i.e.

$$\begin{bmatrix} x_{11} & \dots & x_{1m} \\ x_{21} & \dots & x_{2m} \\ \dots & & \\ x_{n1} & \dots & x_{nm} \end{bmatrix}$$

Then

1. $\bar{u} + \bar{v}$ is in V .
2. $\bar{u} + \bar{v} = \bar{v} + \bar{u}$.
3. $(\bar{u} + \bar{v}) + \bar{w} = \bar{u} + (\bar{v} + \bar{w})$.

4. There is the zero vector $\bar{0} = \begin{bmatrix} 0 & \dots & 0 \\ 0 & \dots & 0 \\ \dots & & \\ 0 & \dots & 0 \end{bmatrix}$

in V such that $\bar{u} + \bar{0} = \bar{u}$.

5. For each $\bar{u} = \begin{bmatrix} x_{11} & \dots & x_{1m} \\ x_{21} & \dots & x_{2m} \\ \dots & & \\ x_{n1} & \dots & x_{nm} \end{bmatrix}$ in V ,

there is the vector $-\bar{u} = \begin{bmatrix} -x_{11} & \dots & -x_{1m} \\ -x_{21} & \dots & -x_{2m} \\ \dots & & \\ -x_{n1} & \dots & -x_{nm} \end{bmatrix}$

in V such that $\bar{u} + (-\bar{u}) = \bar{0}$.

6. The scalar multiple of \bar{u} by c , denoted by $c\bar{u}$, is in V .

7. $c(\bar{u} + \bar{v}) = c\bar{u} + c\bar{v}$.

8. $(c + d)\bar{u} = c\bar{u} + d\bar{u}$.

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10. $1 \cdot \bar{u} = \bar{u}$.

EXAMPLE:

The set P_n of polynomials of degree at most n :

$$\bar{p}(t) = a_n t^n + \dots + a_2 t^2 + a_1 t + a_0$$

where the coefficients a_n, \dots, a_0 and the variable t are real numbers.

EXAMPLE:

The set of all real-valued functions defined on R .

DEFINITION:

A subspace of a vector space V is a subset H of V that has 3 properties:

1. The zero vector of V is in H .

2. H is closed under vector addition.

That is, for each \bar{u} and \bar{v} in H , the sum $\bar{u} + \bar{v}$ is in H .

3. H is closed under multiplication by scalars. That is, for each \bar{u} in H and each scalar c , the vector $c\bar{u}$ is in H .

REMARK:

One can show that a subspace H of a vector space V is a vector space.

EXAMPLE:

The set consisting of only the zero vector $\bar{0}$ in a vector space V is a subspace of V , called the zero subspace and written as $\{\bar{0}\}$.

EXAMPLE:

Given \bar{v}_1 and \bar{v}_2 in a vector space V , let $H = \text{Span} \{\bar{v}_1, \bar{v}_2\}$. Show that H is a subspace of V .

SOLUTION:

First of all, note that

$$\text{Span} \{ \bar{v}_1, \bar{v}_2 \} = \{ \alpha \bar{v}_1 + \beta \bar{v}_2 : \alpha, \beta \in R \}.$$

Therefore $\text{Span} \{ \bar{v}_1, \bar{v}_2 \}$ is a subset of V .

Moreover,

1. The zero vector $\bar{0}$ is in H , since

$$\bar{0} = 0 \cdot \bar{v}_1 + 0 \cdot \bar{v}_2.$$

2. H is closed under vector addition.

In fact, let

$$\bar{u} = s_1 \bar{v}_1 + s_2 \bar{v}_2, \quad \bar{w} = t_1 \bar{v}_1 + t_2 \bar{v}_2.$$

By Axioms 2, 3, and 8 we have:

$$\begin{aligned} \bar{u} + \bar{w} &= (s_1 \bar{v}_1 + s_2 \bar{v}_2) + (t_1 \bar{v}_1 + t_2 \bar{v}_2) \\ &= (s_1 + t_1) \bar{v}_1 + (s_2 + t_2) \bar{v}_2, \end{aligned}$$

therefore $\bar{u} + \bar{w}$ is in H .

3. Similarly, if c is any scalar, then by Axioms 7 and 9 we get

$$c\bar{u} = c(s_1 \bar{v}_1 + s_2 \bar{v}_2) = (cs_1) \bar{v}_1 + (cs_2) \bar{v}_2,$$

therefore $c\bar{u}$ is also in H .

Thus, H is a subspace of V .

THEOREM:

If $\bar{v}_1, \dots, \bar{v}_p$ are in a vector space V , then $\text{Span} \{ \bar{v}_1, \dots, \bar{v}_p \}$ is a subspace of V .